

# V-BELTS

Rubber V-belts



**MEGADYNE**

# INTRODUCTION TO V-BELTS

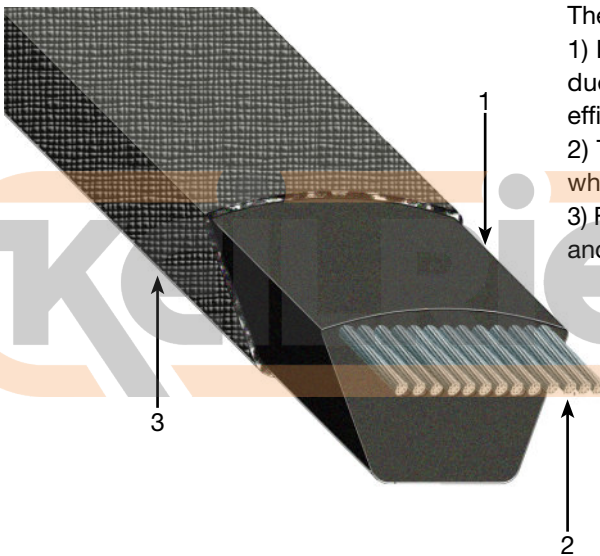


Megadyne V-belts have been used for decades in the most different industries and applications, offering drive solutions to customers all over the world.

Applied technology guarantees such a dimensional precision in V-belts which allows them to be suitable for multiple transmissions. This dimensional stability continues also during belt use.

The variety of belt sizes available allows the application of Megadyne V-belt in a wide range of drive applications, such as:

- machine tools
- industrial washing machines
- textile machines
- continuous paper machines
- high power mills
- stone crushers



The main V-belt components are:

- 1) Belt body made of a special rubber compound which provides, due to its excellent mechanical characteristics, high transmission efficiency and assures a minimum rubber wear off;
- 2) Tensile member consisting in high-strength low-stretch cords, which grant length stability over the belt life time;
- 3) Fabric jacket or cover made of fabric, protecting the tensile member and permitting the use of back side idler.

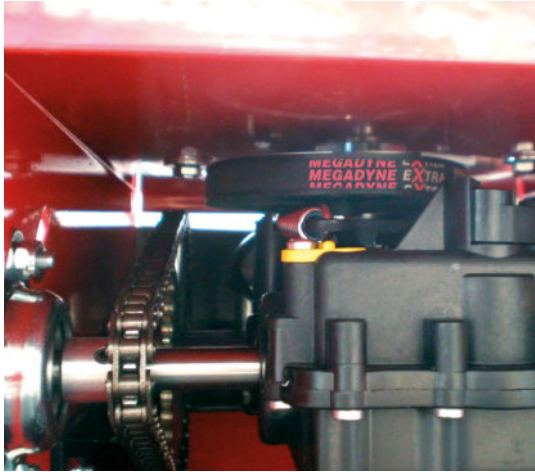
## MECHANICAL AND CHEMICAL FEATURES

- smooth starting and running
- wide range of driven speed
- low maintenance
- high efficiency
- extremely wide horsepower ranges
- dampen vibration between driver and driven pulleys
- silent operations
- long life service
- easy installation
- reduction in drive dimension
- working temperature range from  $-30^{\circ}\text{C}$  to  $+80/90^{\circ}\text{C}$  (see details in family pages)
- oil and heat resistance
- antistatic properties

### MEGAMATCH **MEGA MATCH**

All V-belts carrying the MEGA MATCH logo are made and supplied according to the matching set tolerances and limits indicated by the relevant international standards (ISO, RMA, etc)

# INTRODUCTION TO V-BELTS



## WRAPPED BELTS

### EXTRA

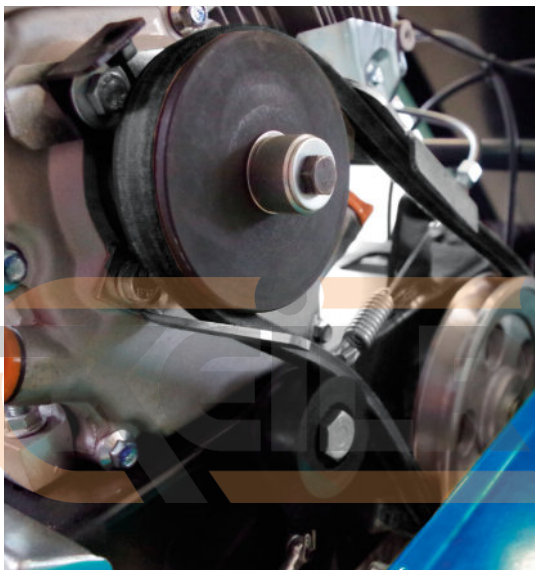
Extra belts were designed to offer durable and reliable performances on light and medium-duty drives. They represent an affordable solution for transmission systems of all industrial sectors.

### OLEOSTATIC

Oleostatic rubber belts are developed with high resistant tensile elements, they are characterised by high performances, length stability during belts life, conductivity, oil and heat resistance. They are particularly suitable for centrifugal pumps, compressor, tool machines, generators, high power mills and stone mills.

### OLEOSTATIC GOLD

Different materials and design features, together with an improved production process, have led to the development of a new class of higher rated wrapped V-belts. The new OLEOSTATIC GOLD V-belts products family can operate in a wide range of industrial applications, within a large spread of load capacities and speeds — offering rated performance from 100 to 8,000 RPM and power capability from 1 to 400 kW, meanwhile granting large cost advantages for the end users.



#### Oleostatic Gold structure:

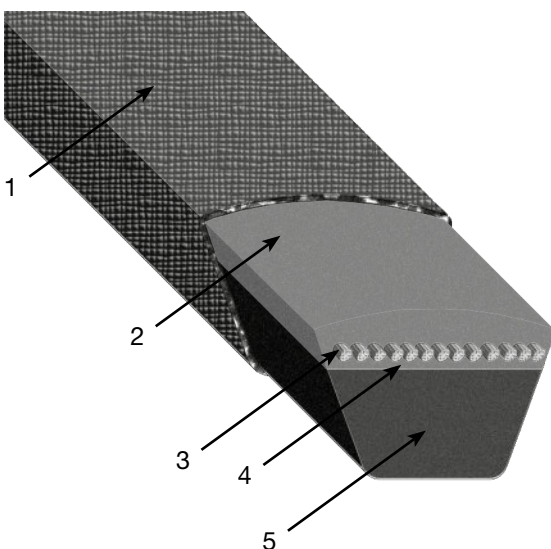
- 1) FABRIC: Double cover ply - CR Dip.

A reinforced, double fabric cover is plied around the belt to protect it against contamination and moisture. Its increased flexibility allows the belt to bend more easily around the smallest pulleys with far less strain on the fabric, while assuring a smoother running drive.

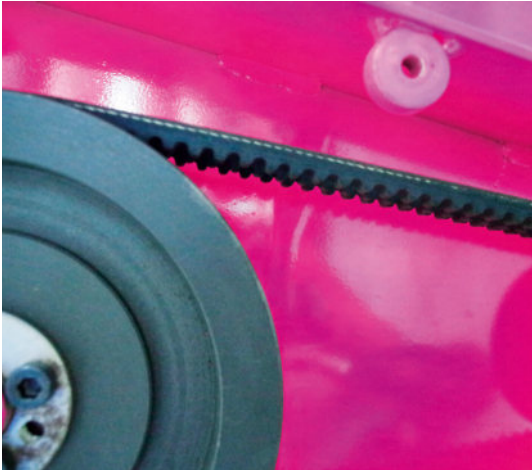
- 2) TOP CUSHION: SBR compound + Fibers
- 3) TENSILE CORD: H.T. Polyester

The tensile section is made up of a multiple number of high-strength, low elongation polyester cords, completely embedded in the adhesion layers, to enhance resistance to tension and flex-fatigue. Each cord is individually and specially coated to secure a long-lasting bond with the surrounding rubber and to grant a longer operational lifetime. In addition the belt requires significantly less retensioning and take-up due to its cord's consistent length stability. Longer belt life means less frequent replacement, less downtime and lower maintenance costs.

- 4) BOTTOM CUSHION: SBR compound + Fibers
- 5) BODY COMPOUND: Polychloroprene (CR) based



# INTRODUCTION TO V-BELTS

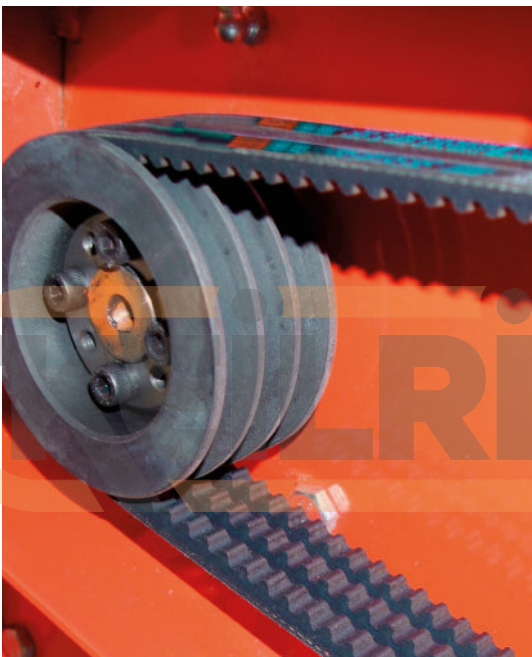


## RAW EDGE

### LINEA-X

These belts have been specifically developed to run where small pulleys diameters and high transmission ratios put a limit to the use of wrapped belts of the same section.

Compared to wrapped belts, the LINEA-X family offers important improvements, like specific compounds and special production technology. In particular the transverse orientation of the fibers improves the cord support capacity of the body section and reinforces its transverse rigidity, while maintaining, (due to the cogged profile and the precision-ground sidewalls) the highest longitudinal flexibility and running stability. These characteristics guarantee an excellent structure with advantages such as: high transmission ratios, improved grip and resistance to continuous bending.



### LINEA GOLD

The NEW generation of raw edge belts

New materials, advanced design features and an innovative production process has led MEGADYNE to develop a new generation of raw edge V-belt drives that outperform, in a wide range of industrial applications, all the previous drives equipped with standard raw edge belts, granting large cost advantages for the end users and greater design flexibility for the engineers. The belt has a narrow cross section and a raw edge construction, based on a new EPDM rubber compound which can withstand chemically aggressive environments, ageing, ozone, UV and heat.

Linea Gold structure:

#### 1) BACKSIDE FABRIC

A textile fabric is plied on the belt backside to protect it against contamination and moisture.

Its flexibility gives the belt excellent reversed bending properties when backside idlers are used and protects the belt against wear.

#### 2) ADHESION LAYERS

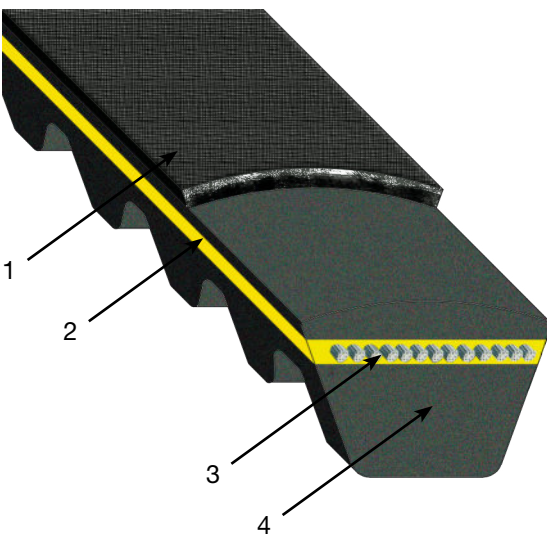
An innovative, colored, EPDM compound located immediately above and below the belt cords, guarantees the best possible bonding with the under cord body material.

#### 3) TENSILE CORD

The tensile section is made up of a multiple number of high-strength, low elongation polyester tensile cords which are completely embedded in the adhesion layers and vulcanized as one solid unit to enhance resistance to tensile and flex-fatigue forces. On request, for special extreme requirements, aramid or glassfibre cords are also available.

#### 4) BODY COMPOUND

A newly developed EPDM compound, with high-performance fibers embodied in the rubber matrix, provides to the belt with superior abrasion and wear resistance. The transversal orientation of the fibers improves the cord support capacity of the body section and reinforces its transversal rigidity, while maintaining, in connection with the cogged profile and the precision-ground sidewalls, the utmost longitudinal flexibility and running stability.



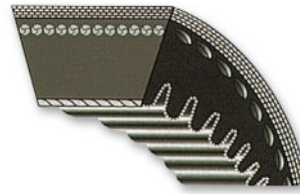


**SECTIONS**

- Z E
- A 20
- B 25
- C 45
- D 50

**Classical wrapped V-belts**

(Extra - Oleostatic - Oleostatic Gold)



**SECTIONS**

- AX
- BX
- CX

**Classical raw edge V-belts**

(Linea Gold)



**SECTIONS**

- SPZ
- SPA
- SPB
- SPC

**Narrow wrapped V-belts DIN**

(Extra - Oleostatic Gold)



**SECTIONS**

- XPZ
- XPA
- XPB
- XPC

**Narrow raw edge V-belts DIN**

(Linea-X - Linea Gold)



**SECTIONS**

- 3V
- 5V
- 8V

**Narrow wrapped V-belts RMA**

(Oleostatic)



**SECTIONS**

- |       |       |
|-------|-------|
| 13x6  | 36x12 |
| 17x6  | 37x10 |
| 21x7  | 42x13 |
| 22x8  | 47x13 |
| 26x8  | 52x16 |
| 28x8  | 55x16 |
| 30x10 | 65x20 |
| 32x10 | 70x20 |

**Variable speed V-belts**

(Varisect)



**SECTIONS**

- XDV2-38
- XDV2-48
- XDV2-58

**Xtra Duty V-belts**

(XDV2)



**SECTIONS**

- AA
- BB
- CC

**Double V-belts**

(Esaflex)

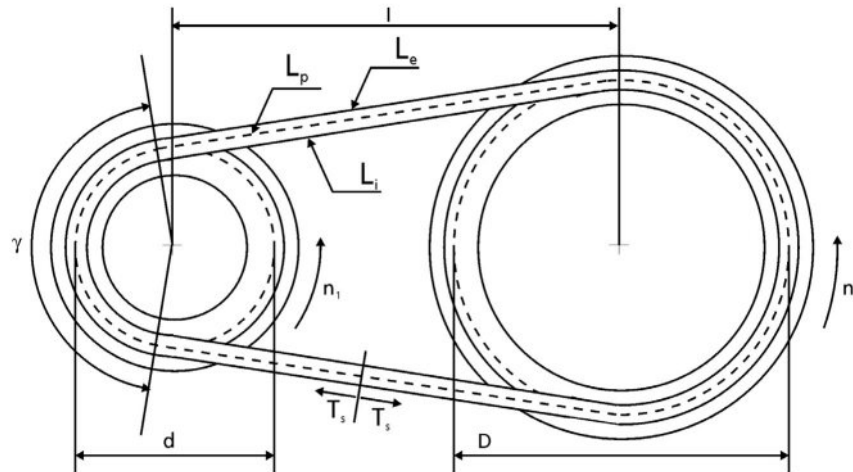


**SECTIONS**

- |      |      |
|------|------|
| RA   | RSPC |
| RB   | R3V  |
| RC   | R5V  |
| RSPZ | R8V  |
| RSPA | R3VX |
| RSPB | R5VX |

**Banded V-belts**

(Pluriband)



Symbol	Unit	Definition	Symbol	Unit	Definition
$C_\gamma$		correction factor $C_\gamma$	$L_p$	mm	pitch length (effective)
$C_L$		correction factor $C_L$	$n_1$	RPM	speed of smaller pulley (faster)
$C_c$		correction factor $C_c$	$n_2$	RPM	speed of bigger pulley (slower)
$d$	mm	pitch diameter of smaller pulley	$P$	kW	power to be transmitted
$D$	mm	pitch diameter of bigger pulley	$P_a$	kW	actual power of the transmission
$I$	mm	theoretical center distance	$P_b$	kW	basic performance of a single belt
$I_e$	mm	effective center distance	$P_c$	kW	corrected power
$i$		transmission ratio	$P_d$	kW	difference to $P_b$ due to $K \neq 1$
$L'$	mm	calculated pitch length	$Q$		number of belts
$L_e$	mm	external length ( $L_p + \Delta$ )	$T_s$	N	static belt tension
$L_i$	mm	internal length ( $L_p - \Delta$ )	$v$	m/s	peripheral belt speed
			$\gamma$	°	arc of contact

## BELT SECTION

Necessary data for selection of the belt section:

$P$  = power to be transmitted in kW

$n_1$  = speed in RPM of the smaller pulley

$n_2$  = speed in RPM of the bigger pulley

It is necessary to correct the power  $P$  by a coefficient  $C_c$  (see table 1 page 6) which considers into account the actual operating conditions.

Corrected power  $P_c$  is given by:

$$P_c = P \cdot C_c$$

The graphs gives a guiding criterion for the section of the belt.

## TRANSMISSION RATIO

Transmission ratio is calculated as follows:

$$i = \frac{n_1}{n_2} = \frac{D}{d}$$

where  $D$  is the pitch diameter of larger pulley and  $d$  is the pitch diameter of the smaller pulley.

## TECHNICAL CALCULATION

Peripheral speed of the belts is determined by

$$v = \frac{d \cdot n_1}{19100}$$

If the drive being calculated is of the V/flat type (one V pulley and one flat pulley) it is necessary to find the corresponding pitch diameter of the flat pulley.

The pitch diameter of the flat faced pulley is obtained by increasing its external diameter by the amount in millimetres shown in the following table:

Z	A	B	C	D	E	19	20	25
8	10	14	20	24	33	16	15	19

## PITCH LENGTH OF THE BELT AND CORRECT CENTER DISTANCE

Whenever the shaft center distance  $l$  is not predetermined by the layout of the drive, the optimum distance may be chosen as follows:

$$1 < i < 3 \quad l \geq \frac{(i+1) \cdot d}{2} + d$$

$$i > 3 \quad l \geq D$$

The pitch length is determined by:

$$L' = 2 \cdot l + 1,57 \cdot (D+d) + \frac{(D-d)^2}{4l}$$

From the list of belt sizes, should be selected the belt pitch length  $L_p$  nearest to the value of  $L'$  above calculated. Since  $L' \neq L_p$  the center distance " $l$ " may be varied by subtracting half  $L' - L_p$ . Therefore the effective center distance of the drive will be:

$$l_e = l - \frac{(L' - L_p)}{2}$$

## NUMBER OF BELTS

The basic performance  $P_b$  is the power which a single belt transmits under the following conditions:

- $i = 1$

This configuration corresponds to 180° arc of contact belt on both pulleys;

- $i \neq 1$

The difference of kW-rating  $P_d$  is the power which the belt transmits in excess of  $P_b$  because  $i \neq 1$  in service conditions. The actual kW-rating  $P_a$  is the power which the belt transmits in operating conditions and is obtained by means of:

$$P_a = (P_b + P_d) \times C_g \times C_L$$

Table 4 (see belt family pages) gives the values of  $P_b$  according to RPM and  $d$  (smaller diameter) and the values of  $P_d$  according to RPM and  $i$ .

Table 2 (bottom of this page) and 3 (see belt family pages) give values of the coefficients  $C_\gamma$  and  $C_L$  taking into account the operating conditions.

The arc of contact  $\gamma$  of the belt on the smaller pulley is determined by:

$$\gamma = 180^\circ - 57 \cdot \frac{D-d}{l_e}$$

The number of belts  $Q$  necessary for the transmission of the power  $P_c$  is determined by:

$$Q = \frac{P_c}{P_a}$$

The number of belts actually is obtained in general by rounding up  $Q$  to the next highest whole number.

## TABLE 1 - TYPE OF MOTOR

Applications	Drivers					
	(1)			(2)		
	Daily operating hours					
	0-8 <sup>(1)</sup>	8-16 <sup>(1)</sup>	16-24 <sup>(1)</sup>	0-8 <sup>(2)</sup>	8-16 <sup>(2)</sup>	16-24 <sup>(2)</sup>
<b>Light use</b> Centrifugal pumps and compressors, belt conveyors, (light materials) fans and pumps up to 7,5 kW.	1,1	1,1	1,2	1,1	1,2	1,3
<b>Normal use</b> Shears for steel sheet presses, belt and chain conveyors, (heavy material) sifters, generator sets, machine tools, kneading machines, industrial washing machines, printing presses, fans and pumps over 7,5 kW.	1,1	1,2	1,3	1,2	1,3	1,4
<b>Heavy use</b> Hammer mills, piston compressors, belt conveyors for heavy loads, lifters, textile machines, continuous paper machines, piston and dredging pumps, ripping saws.	1,2	1,3	1,4	1,4	1,5	1,6
<b>Extra heavy use</b> High power mills, stone crushers, calendars, mixer, cranes, diggers, dredgers.	1,3	1,4	1,5	1,5	1,6	1,8

## TABLE 2 - Correction factor $C_\gamma$ (T/T=V/V drives; T/P=V/Flat drives; $\gamma$ =arc of contact on the smaller pulley)

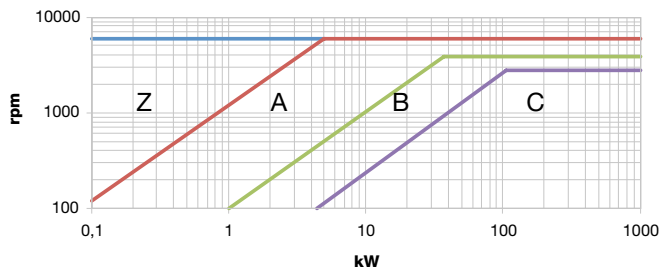
$\gamma$	180°	175°	170°	165°	160°	155°	150°	145°	140°	135°	130°	125°	120°	115°	110°	105°	100°	90°	
$C_\gamma$	T/T	1	0,99	0,98	0,96	0,95	0,93	0,92	0,90	0,89	0,87	0,86	0,84	0,82	0,80	0,78	0,76	0,74	0,69
	T/P	0,75	0,76	0,77	0,79	0,80	0,81	0,82	0,83	0,84	0,85	0,86	0,84	0,82	0,80	0,78	0,76	0,74	0,69



# WRAPPED V-BELTS SELECTION CHARTS

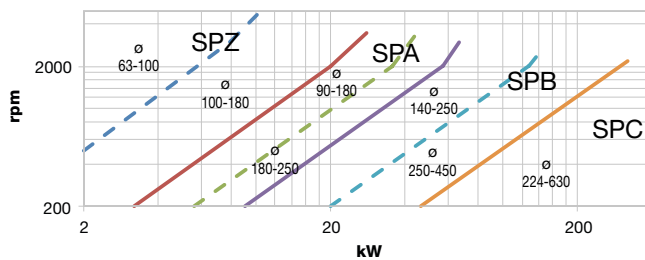
## Classical wrapped V-belts

### EXTRA

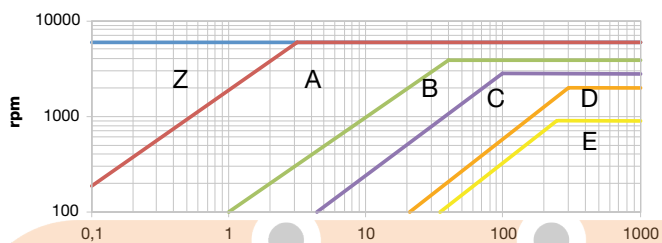


## Narrow wrapped V-belts DIN

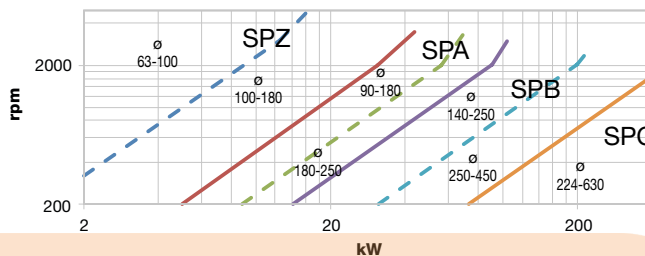
### EXTRA



## OLEOSTATIC GOLD

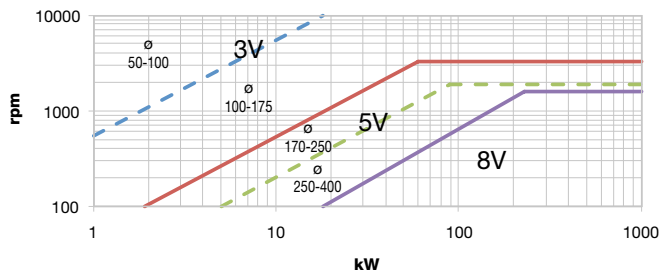


## OLEOSTATIC GOLD

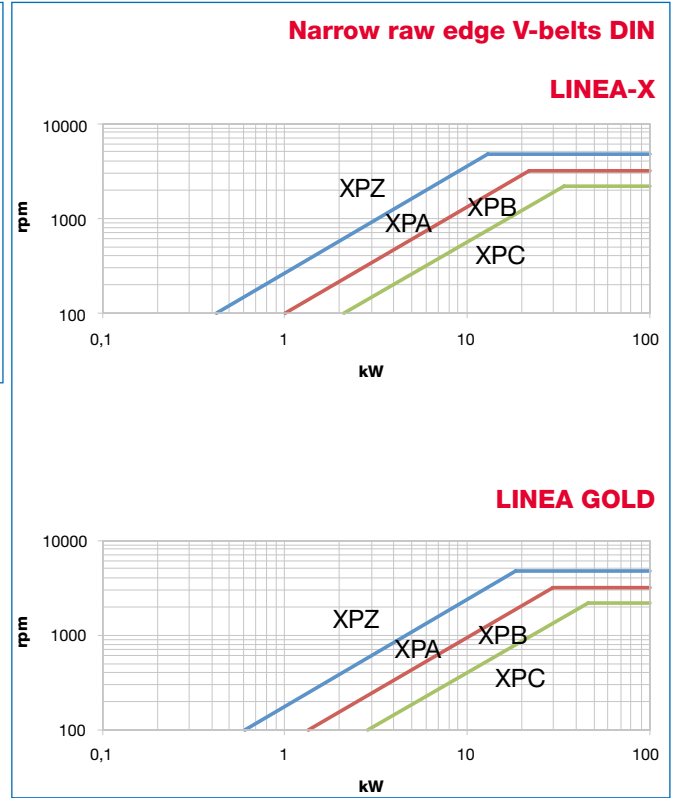
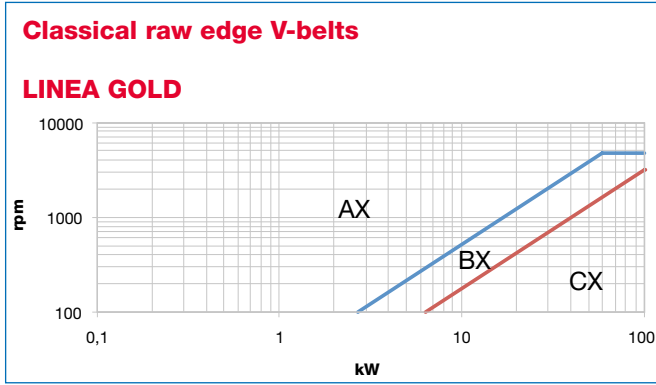


## Narrow wrapped V-belts RMA

### OLEOSTATIC



# RAW EDGE V-BELTS SELECTION CHARTS



# KEILRIEMEN.AT

## CALCULATION EXAMPLE

### EXAMPLE

$P = 22 \text{ kW}$

$n_1 = 1200 \text{ RPM}$

$n_2 = 660 \text{ RPM}$

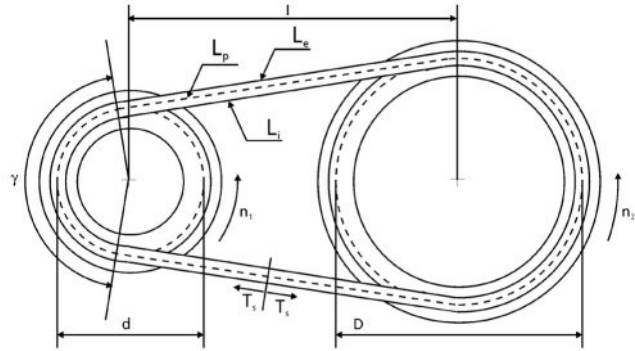
Textile machine operating 12 hours a day

Type of motor: ac electric motor, normal torque

The correction coefficient is 1,3 (see table 1)

The corrected power is:

$$P_c = 22 \cdot 1,3 = 28,6 \text{ kW}$$



## BELT SELECTION

From selection charts, for  $P_c = 28,6$  and  $n_1 = 1200 \text{ RPM}$  it is appropriate to choose section B.

## TRANSMISSION RATIO

The transmission ratio can be calculated as follows:

$$i = \frac{n_1}{n_2} = \frac{1200}{660} = 1,82$$

Considering diameter  $d = 250 \text{ mm}$  for the smaller pulley, the pitch diameter of the larger pulley is:

$$D = i \cdot d = 1,82 \cdot 250 = 455 \text{ mm}$$

Peripheral speed of the belts is determined by

$$v = \frac{d \cdot n_1}{19100}; \quad v = \frac{0,052 \cdot 250 \cdot 1200}{19100} = 15,7 \text{ m/s}$$

## BELT PITCH LENGTH AND CORRECT CENTER DISTANCE

For  $i = 1,82$  (i.e.  $1 < i < 3$ ) the center distance is given by:

$$l \geq \frac{(i+1) \cdot d}{4} + d \quad \text{so} \quad l = 610 \text{ mm}$$

The pitch length of the belt is determined by:

$$L' = 2 \cdot l + 1,57 \cdot (D+d) + \frac{(D-d)^2}{4 \cdot l};$$

$$L' = 2 \cdot 610 + 1,57 \cdot (455+250) + \frac{(455-250)^2}{4 \cdot 610} = 2344 \text{ mm}$$

From the list of belt sizes (see table on belt family pages), should be selected the belt pitch length  $L_p$  nearest to the value of  $L'$  previously calculated.

The center distance "l" may be varied by subtracting half  $L' - L_p$ . Therefore the effective centre distance of the drive will be:

$$l_e = l - \frac{L' - L_p}{2}$$

Having selected **Oleostatic Gold B 91** ( $L_p = 2355 \text{ mm}$ ), the actual shaft center distance is calculated by:

$$l_e = 610 - \frac{2344 - 2355}{2} = 615,5 \text{ mm}$$

From table 4 of B section (d=250 mm; 1200 RPM; K=1,82):

$$P_b = 11,57 \text{ kW}$$

$$P_d = 0,48 \text{ kW}$$

The arc of contact  $\gamma$  of the belt on the smaller pulley is determined by:

$$\gamma = 180^\circ - 57 \cdot \frac{D-d}{l_e} = 180^\circ - 57 \cdot \frac{455-250}{616} \cong 161^\circ$$

From table 2 for  $\gamma = 161^\circ$

$$C_\gamma = 0,95$$

From table 3, pag 19 for **Oleostatic Gold B 91** belt

$$C_L = 1,00$$

Therefore:

$$P_a = (11,57+0,48) \cdot 0,95 \cdot 1,00 = 11,45 \text{ kW}$$

The number of belts Q necessary for transmission of the power  $P_c$  is established by:

$$Q = \frac{P_c}{P_a} = \frac{28,6}{11,45} = 2,5$$

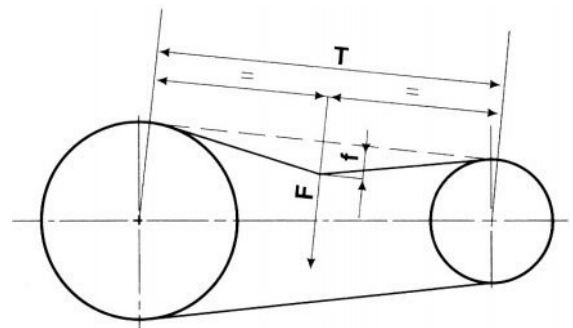
Round up to 3 belts **Oleostatic Gold B 91**.

## BELT TENSIONING RECOMMENDATION

The correct belt assembling tension is given by:

$$T_s = 500 \cdot \frac{2,5-C_\alpha}{C_\alpha} \cdot \frac{P_c}{Q \cdot v} + m \cdot v^2$$

Symbol	Unit	Definition
$C_\alpha$		arc correction factor
$m$	kg/m	belt linear mass (see belt family page)
$P_c$	kW	corrected power
$Q$		number of belts
$T_s$	N/strand	static belt tension
$v$	m/s	peripheral belt speed
$\alpha$	°	arc of contact



Arc correction factor:

$\alpha$ [°]	180	174	169	163	157	151	145	139	133	127	120	113	106	99	91	83
$C_\alpha$	1,00	0,98	0,97	0,96	0,94	0,93	0,91	0,89	0,87	0,85	0,82	0,80	0,77	0,73	0,70	0,65

# LENGTH MEASURING AND GROOVE PULLEYS

## BELT LENGTH MEASURING

The first and easiest way for measuring the V-belt length is by placing the belt on a flat surface, giving the belt a circular shape and finally measuring the internal length  $L_i$  by means of a measuring tape. Adding  $\Delta_i$  and after  $\Delta_e$  (see belt families pages) to this length, it's possible to calculate respectively  $L_p$  and  $L_e$ .

This measuring way is not very precise, even if practically easy and feasible with a tape only.

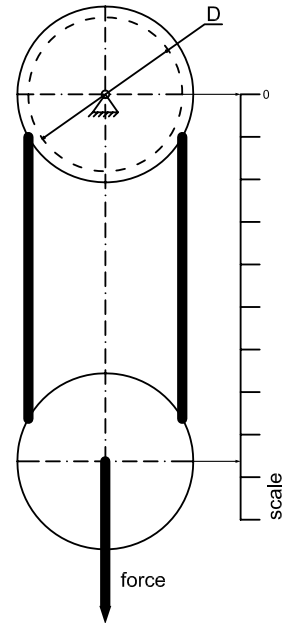
The correct way for measuring the V-belt length is by means of pulleys and dynamometer. The belt is put on 2 pulleys, specific for the family and size of the belt and having the same pitch diameter. One is fixed while the second can move on a linear graduated scale. Depending on the belt, a certain force is applied to the second pulley in order to put the complete system under tension. The correct force is tabled the relevant standards referring to the belt family.

To stabilize the system, at least 3 rotations of the pulleys are required.

The pitch length  $L_p$  is given by the pulleys pitch diameter  $D$  and center distance  $a$  in the formula:

$$L_p = 2 a * \pi_D$$

Subtracting  $\Delta_i$  and adding  $\Delta_e$  (see belt families pages) it's possible to calculate respectively  $L_i$  and  $L_e$ .



## GROOVE PULLEYS

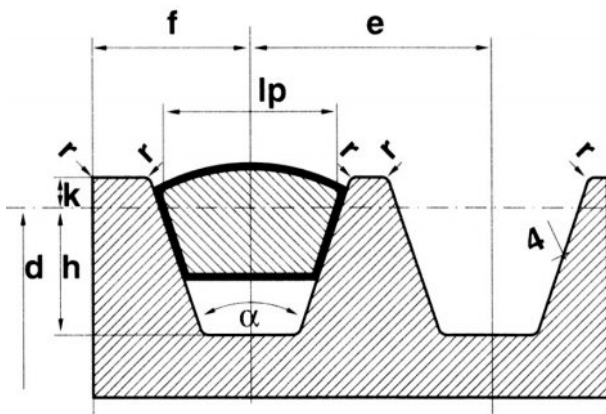
Groove pulleys for V-belts must be manufactured with care and be made of good quality steel or engineering cast iron. It is most important that the flanks of the grooves shall be perfectly smooth and show no visible sign of machining, that all sharp corners of the grooves shall be rounded off and chamfered and that the external diameter of the face shall be constant overall.

All pulleys must also be statically balanced.

Dynamic balancing is required for speeds over 30 m/second.

Profile and dimension of pulley should be in accordance to DIN 2211, BS 3790, ISO, RMA depending on the belt relevant standard.

In the drawing are shown the main characteristics and dimensions of groove pulleys for V-belts (example referring to Oleostatic belts).



- lp** = pitch width
- k** = minimum height of groove above the pitch line
- h** = minimum depth of groove below the pitch line
- alpha** = groove angle
- d** = pitch diameter
- e** = distance between the axes of the sections of two grooves
- f** = distance between the axis of the section of the outer groove and the rim of the pulley

# LENGTH MEASURING AND GROOVE PULLEYS

The use of idlers in V-belt drives is not recommended.

However, due to particular drive requirements and limitations, use of idlers may be absolutely necessary.

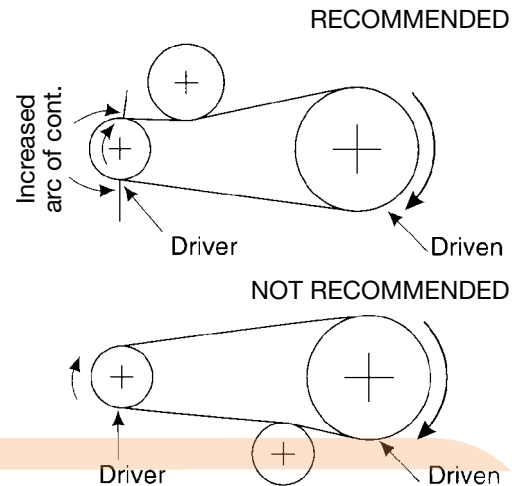
For using idlers, requirements are as follows:

1. Providing take-up for fixed center drives.
2. Turning corners (as in mule pulley drives).
3. Breaking up long spans where belt whip may be a problem.
4. Maintaining tension, when idler is spring-loaded or weighted.

A power correction (see below) is required.

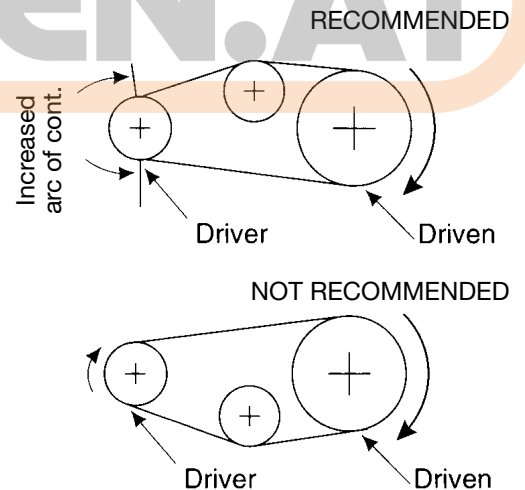
## OUTSIDE IDLER

1. An outside idler should be at least one and one-third times as large as the smallest pulley on the drive, unless drive has unusually large pulleys.
2. An outside idler must be flat and without any crown.
3. To find the face width of a flat idler (between flanges if flanged) add 1 ½ times the nominal belt top width to the face width of the grooved pulley used.
4. An outside idler pulley should be located as close as possible to the preceding pulley. This is because V-belts move back and forth slightly on a flat pulley and locating it as far away from the next pulley minimizes the possibility of the belt entering that pulley in a misaligned condition.
5. Idler pulleys should be located only on the slack side of a drive.



## INSIDE IDLER

1. An inside idler will decrease the arc of contact.
2. An inside idler should be at least as large as the smallest pulley on the drive, unless the drive has unusually large pulleys.
3. An inside idler should better be a grooved pulley. In alternative, flat pulleys can be used.
4. A grooved inside idler pulley may be located anywhere along the span, preferably so that it gives nearly equal arcs of contact on the two adjacent pulleys.
5. Idler pulleys should be located only on the slack side of a drive.



## RATED POWER CORRECTION

Because idlers impose an additional bending stress point on the V-belt, the transmittable power is reduced.

The smaller the idler diameter, the greater the bending stress, which results in a greater reduction in rated power and belt life.

To compensate this loss, the design power of the drive must be increased.

The following table gives the approximate correction factors according to the number of pulleys in the drive.

The normal power rating should be multiplied by this factor.

No. of pulleys in drive	2	3 (one idler)	4 (two idlers)
Rating Correction Factor	1,00	0,90	0,80

### Note:

As stated, the above listed factors are only approximate values and apply only when idler diameters and their location is in accordance with the above recommendations.

# STORAGE MAINTENANCE AND USEFUL ADVICES

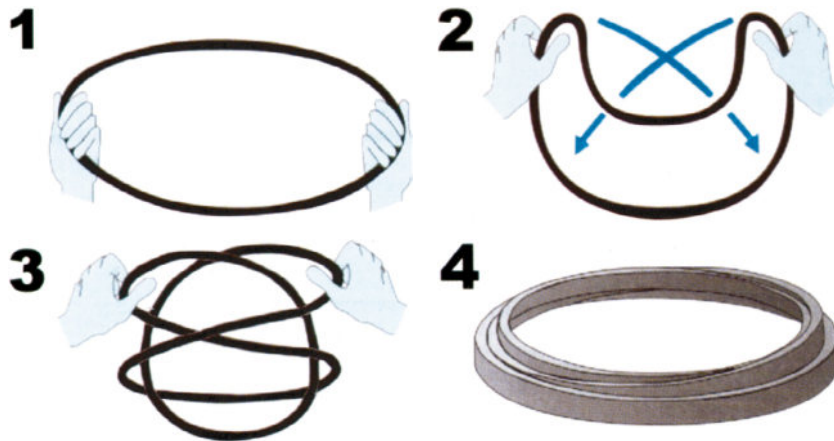
## HOW TO STORE BELTS

In order to store V-Belts correctly, it is advisable to hang them on “saddles” or on large-diameter tubular brackets. This diameter should be at least ten times the height of belts cross section.

Long belts can be stacked to save space, provided that they are correctly coiled (see figures).

Short belts can be stored on shelves, but be aware that stacks should not be more than 300 mm high, as the bottom belts may be otherwise deformed.

Finally, hooks and nails are unsuitable for suspending the belts.



## CONDITIONS OF STORAGE

Rubber V-belts can be stored for several years without causing any performance or reliability loss.

For a correct storage, some prescription have to be taken into account.

- Environment

The storage premises should be cool, dry and well ventilated but not draughty.

- Temperature

Storage temperature should be within +5 and +30°C.

Lower temperatures causes stiffening in the belt but are accepted in the storage. In order to avoid damages in the start-up, it becomes necessary to heat the belt up to around 20° before making it run on the machine.

Higher temperatures due to heating are to be avoided. Distance from heating sources should be at least 1 meter.

- Light

Belts should be protected from light, especially direct sunlight and artificial light with high ultraviolet rays (neon light).

- Ozone

Equipments generating ozone, like high voltage electrical machines or fluorescent light sources, should not be installed in the storage.

Also combustion gases and vapours, that can cause ozone, should be avoided.

- Chemicals

Flammable materials, lubricants, acids and any other aggressive material should not be kept in the storage. Belts elastomers may be affected or even irreparably damaged by such agents.

## CLEANING

Never clean V-belts. If you need, for any reason, to clean belts use a dry towel or one soaked with a glycerine/alcohol mixture in the ratio 1:10. Other solvents such as petrol or benzene must not be used.

Sharp-edged objects must not be used for cleaning V-belts.

To ensure a long service life and high performances, it is important to design correctly the application and to take care of correct installation, maintenance and storage of the belt.

A drive must be designed in such a way to make proper provision for both installation and tensioning of the V-belts. For this purpose a take-up device is necessary; a slide adjuster on the motor is recommended to simplify installation and permit optimum tensioning.

Table 5 (see belt family pages) provides minimum variation of center distance permitted for installation and tensioning of the belts.

x	=	Take up allowance
y	=	Installation allowance
l	=	Center distance

Furthermore, the following rules must always be observed:

- 1) check the alignment of the drive pulleys;
- 2) make sure that the flanks of the grooves are clean;
- 3) adjust the tensioner to stretch the belts sufficiently;
- 4) check the tension (see following section);
- 5) check correct diameter for tensioning pulley;
- 6) protect belt from oil and other chemicals;
- 7) when installing belts, slack off tensioner and avoid using tools or implements which may damage the belts.

Pulleys with large diameters increase belt life. They must be statically balanced up to the speed of 30 m/s and dynamically balanced over this value.

## TENSIONING SYSTEM

The satisfactory performance of a transmission equipped with V-belts depends on the correct fitting tension. It is therefore necessary to proceed in the following way, using the slide adjuster:

### Belt tension control by deflection method

The approximate relation among deflection force, belt deflection and belt tension is given by:

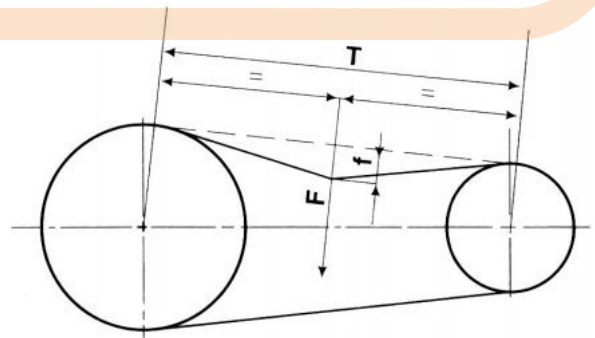
$$T_s \approx \frac{f \cdot t}{4 \cdot f}$$

Imposing a belt deflection

$$f = \frac{t}{64}$$

the deflection force should be in the range

$$F_{\min} \approx F' = \frac{T_s}{16} \quad F_{\max} \approx F'' = \frac{1,5 \cdot T_s}{16}$$



where:

Symbol	Unit	Definition
<b>F</b>	N	perpendicular deflection force
<b>f</b>	mm	belt deflection
<b>t</b>	mm	free span length
<b>T<sub>s</sub></b>	N/strand	static belt tension (see page 9)

Belt tension control by vibration method

$$\text{Belt vibration frequency: } F_r^2 = \frac{T_s}{4 \cdot m \cdot t^2}$$

Symbol	Unit	Definition
<b>F<sub>r</sub></b>	Hz	natural frequency of belt
<b>m</b>	kg/m	specific belt mass
<b>t</b>	m	free span length
<b>T<sub>s</sub></b>	N/strand	static belt tension (see page 9)

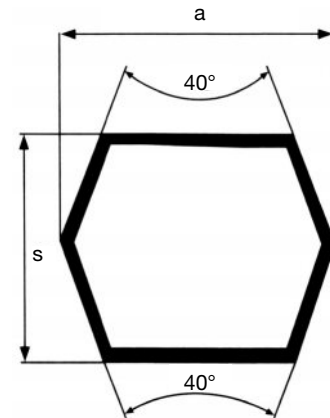


## DOUBLE V-BELTS



## BELT CHARACTERISTICS

section	AA	BB	CC
a (mm)	13	17	22
s (mm)	10	14	19
pitch length - internal length = $\Delta i$ (mm)	31,4	44	59,7
external length - pitch length = $\Delta e$ (mm)	31,4	44	59,7
weight (gr/m)	150	238	429
min. pulley diam. (mm)	80	140	224
working temperature	-30°C / +80°C		
relevant standards	RMA/MPTA IP2 21 - DIN 7722 - ISO 5289		
relevant antistatic standard	ISO 1813		
materials	CR blend - polyester cord - cotton/polyester fabric		



## DOUBLE ANGLE V-BELT

Ideally suited for serpentine drives where power needs to be transmitted equally from both sides of the belt. Double-wrapped cotton-neoprene cover is added for excellent resistance to abrasive wear, heat, ozone, sunlight, grease, oil or dirt.

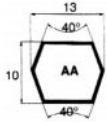
Centrally located cord and special synthetic rubber compounds assure long belt life and smooth, capable power capacity.

Double wrapped neoprene and cotton fabric

The core of the belt is made of a special blend of compounds to provide long life and superior power capacity

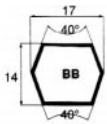


# DOUBLE V-BELTS Esaflex



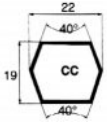
## AA SECTION

Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)
AA 51	1350	AA 69	1805	AA 80	2085	AA 91	2365	AA 108	2800	AA 128	3305	AA 148	3810
AA 60	1580	AA 71	1855	AA 81	2110	AA 95	2465	AA 112	2895	AA 130	3355	AA 163	4195
AA 61	1600	AA 75	1955	AA 85	2210	AA 96	2490	AA 116	3000	AA 134	3455		
AA 68	1780	AA 77	2010	AA 90	2340	AA 105	2720	AA 120	3100	AA 147	3785		



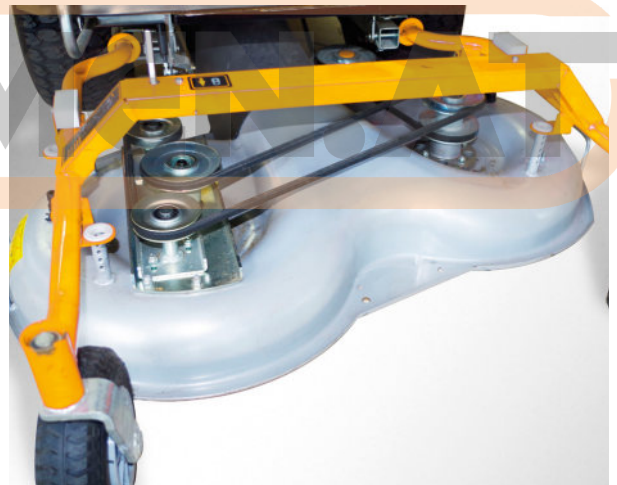
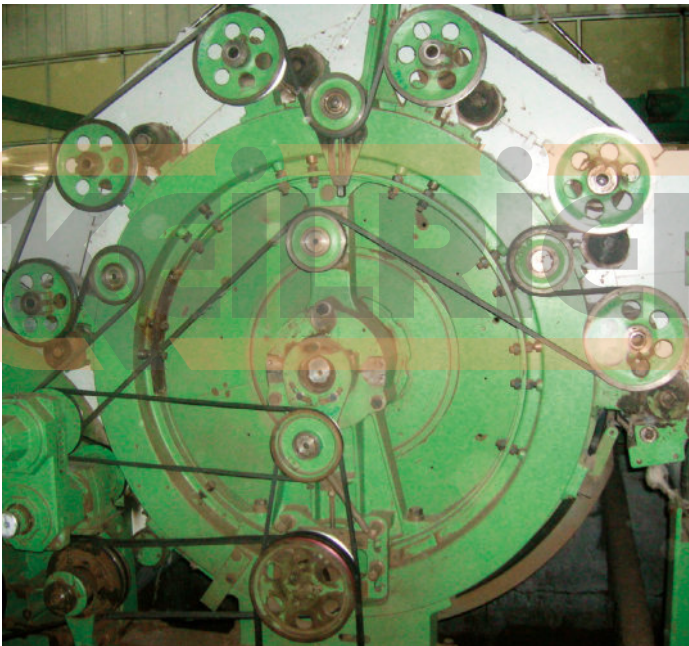
## BB SECTION

Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)
BB 50	1345	BB 84	2210	BB 105	2745	BB 121	3150	BB 155	4015	BB 180	4650	BB 210	5410
BB 60	1600	BB 85	2235	BB 112	2920	BB 128	3325	BB 158	4090	BB 184	4750	BB 240	6135
BB 75	1980	BB 90	2360	BB 118	3075	BB 144	3735	BB 173	4470	BB 190	4900	BB 270	6895
BB 81	2130	BB 97	2540	BB 120	3125	BB 154	3990	BB 174	4495	BB 195	5030	BB 300	7660



## CC SECTION

Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)	Code	Nominal length (mm)
CC 75	2010	CC 90	2390	CC 120	3150	CC 158	4120	CC 193	5010	CC 240	6155	CC 330	8435
CC 81	2160	CC 96	2545	CC 128	3355	CC 162	4220	CC 195	5060	CC 270	6910	CC 360	9200
CC 85	2265	CC 105	2770	CC 144	3760	CC 173	4500	CC 210	5440	CC 300	7675	CC 390	9960
CC 86	2290	CC 112	2950	CC 153	3990	CC 180	4680	CC 234	6000	CC 313	8000	CC 420	10720



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# DATA SHEET FOR CALCULATION

## CUSTOMER DATA

Date \_\_\_\_/\_\_\_\_/\_\_\_\_

Company Name \_\_\_\_\_  
 Address \_\_\_\_\_ Zip Code \_\_\_\_\_  
 City \_\_\_\_\_ State \_\_\_\_\_ Country \_\_\_\_\_  
 Customer Name/Surname \_\_\_\_\_  
 Office \_\_\_\_\_ Tel. \_\_\_\_\_ Fax \_\_\_\_\_  
 e-mail \_\_\_\_\_

Application field \_\_\_\_\_

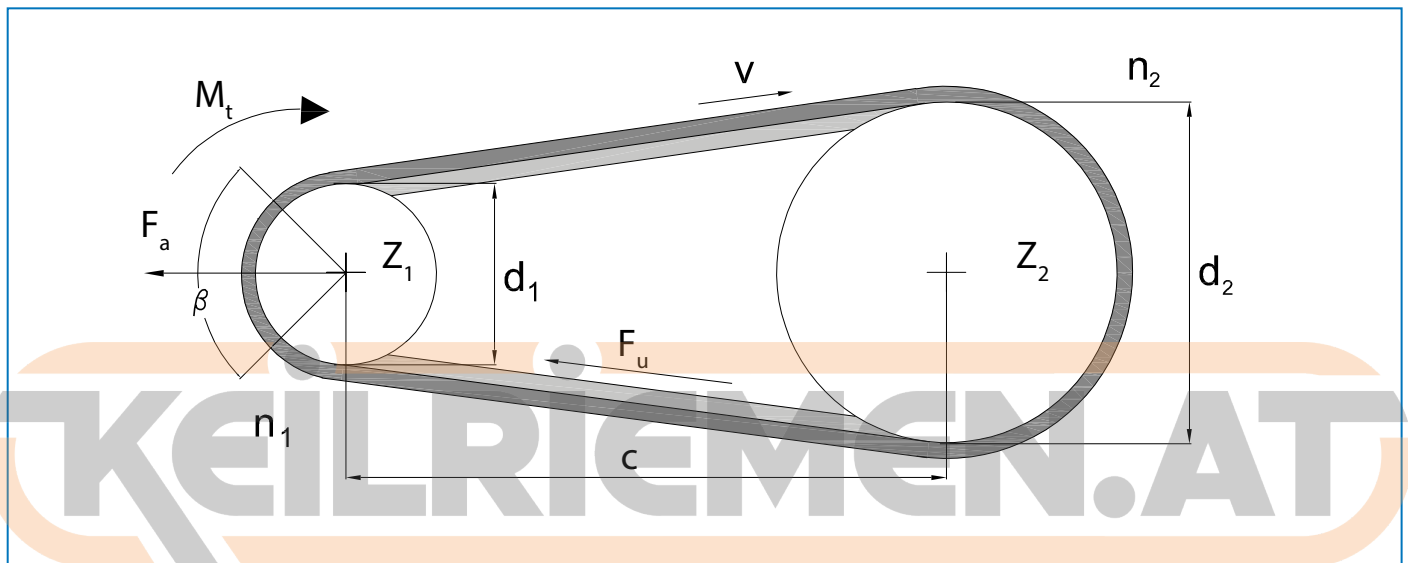
Volume: \_\_\_\_\_

 New

 Existing\*

\*Please enclose to this request all the details of the existing application (competitor's belt, current data, etc..)

## POWER TRANSMISSION TRANSMISSION LAYOUT



If layout is different please sketch it below

## DRIVE INFORMATION

### MOTOR:

AC  DC  Soft Start  Inverter  
 Power: \_\_\_\_\_  
 Speed: \_\_\_\_\_  
 Torque: \_\_\_\_\_  
 Acceleration: \_\_\_\_\_  
 Working time:  < 8h  From 8h up to 16h  >16h

### APPLICATION:

Driver pulley diameter: \_\_\_\_\_  
 Driven pulley diameter: \_\_\_\_\_  
 Center distance: \_\_\_\_\_  
 Minimum safety factor required: \_\_\_\_\_  
 Are there any size limitation?  Yes  No  
 (if yes please indicate):  
 diameter (min. and/or max.): \_\_\_\_\_  
 width (min. and/or max.): \_\_\_\_\_  
 center distance: (min. and/or max.) \_\_\_\_\_